

**IN THE CLAIMS:**

Please **cancel claims 1 and 10** without prejudice to or disclaimer of the subject matter contained therein.

Please **rewrite claims 2-8 and 11-17** as follows:

**2. (Amended)** The noise controller of claim **6**, further comprising:

a signal amplifying part amplifying said noise signal from said sensor part;

a first low pass filter filtering said amplified noise signal from said signal amplifying part and outputting a filtered noise signal to said phase perceiving part and said micro computer part;

a second low pass filter filtering said noise control signal from said micro computer part;

an electric power amplifying part amplifying a filtered noise control signal from said second low pass filter; and

an output part outputting an amplified filtered noise control signal from said electric power amplifying part.

**3. (Amended)** The noise controller of claim **6**, wherein said micro computer includes an index table.

**4. (Amended)** The noise controller of claim **6**, wherein said micro computer includes a neural net.

5. (Amended) The noise controller of claim 6, wherein said micro computer includes a control rule controlling part (CRCP) generating said noise control signal to minimize said residual noise signal.

6. (Amended) A noise controller for actively controlling noise, the controller comprising:

a sensor part perceiving a noise and outputting a noise signal corresponding to said noise;

a phase perceiving part perceiving a phase of said noise signal and outputting a phase signal; and

a micro computer part generating a noise control signal based on a residual noise signal and an error variation signal, said microcomputer including a mixer mixing said noise signal and said noise control signal for generating said residual noise signal and said error variation signal.

7. (Amended) A noise controller for actively controlling noise, the controller comprising:

a sensor part perceiving a noise and outputting a noise signal corresponding to said noise;

a phase perceiving part perceiving a phase of said noise signal and outputting a phase signal, said phase perceiving part including a transformer transforming said noise signal, a full-wave rectifier rectifying a transformed noise signal from said transformer, a pressure-sensitive circuit converting a

fully rectified signal from said full-wave rectifier, and a bandpass filter bandpass filtering a converted signal from said pressure-sensitive circuit; and a micro computer part generating a noise control signal based on a residual noise signal and an error variation signal.

*Enclosed*  
*AS*  
**8.** (Amended) The noise controller of claim **6**, wherein a frequency of said noise signal is a multiple of a base frequency.

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**11.** (Amended) The method of claim **15**, further comprising:

amplifying said noise signal;  
low pass filtering said amplified noise signal;  
low pass filtering said noise control signal;  
power amplifying said filtered noise control signal; and  
outputting said power amplified filtered noise control signal.

**12.** (Amended) The method of claim **15**, wherein said noise control signal is generated through the use of a look up table based on values said residual noise signal and said error variation signal.

**13.** (Amended) The method of claim **15**, wherein said residual noise signal and said error variation signal are generated through the use of a neural net.

**14.** (Amended) The method of claim **15**, wherein said noise control signal is generated to minimize said residual noise signal.

**15.** (Amended) A method of actively controlling noise, the method comprising:

perceiving a noise and generating a noise signal;

perceiving a phase of said noise signal and generating a phase signal;

and

generating a noise control signal based on a residual noise signal and an error variation signal,

wherein said noise signal and a noise cancellation signal are mixed for generating said residual noise signal and said error variations signal.

**16.** (Amended) A method of actively controlling noise, the method comprising:

perceiving a noise and generating a noise signal;

perceiving a phase of said noise signal and generating a phase signal, said phase perceiving step comprising transforming said noise signal, full-wave rectifying said transformed noise signal, converting said fully rectified signal, and bandpass filtering said converted signal; and

generating a noise control signal based on a residual noise signal and an error variation signal.

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17. (Amended) The method of claim 15, wherein a frequency of said noise signal is a multiple of a base frequency.